An Overview of CADP 2001

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CADP

- CAESAR/ALDEBARAN Development Package
- A toolbox for protocol and distributed systems engineering
- Main features:
 - modelling using process algebras (LOTOS)
 - equivalence checking (bisimulations)
 - model checking (modal mu-calculus)
 - exhaustive, partial, on the fly, compositional verification
 - C code generation, rapid prototyping
 - step by step simulation, random execution
 - test generation



Origins of CADP

- Work initiated in 1986
- Joint work between
 - the VASY team of INRIA
 - the Verimag laboratory
 - with contributions of
 - the PAMPA team of IRISA
 - the FMT group at the University of Twente



Main applications of CADP

- Industrial case-studies
 - hardware, software, telecom, embeded systems...
 - formal specification of critical systems and protocols
 - simulation, rapid prototyping, verification, testing
- Research
 - analysis of new systems/protocols
 - experimentation of new verification/testing algorithms
 - implementation of new modelling languages
- Education
 - concurrency, process algebras, bisimulations, model checking
 - robust tools for lab exercises and student projects



Outline

- LOTOS and the Labelled Transition Systems model (LTSs)
- Tools for LOTOS
- Tools for explicit LTSs
- Tools for implicit LTSs
- Tools for compositional verification
- CADP architecture
- Conclusion



LOTOS and the Labelled Transition Systems (LTS) model



LOTOS

Language Of Temporal Ordering Specification [ISO-8807:1989]

- A Formal Description Technique for the specification of protocols and distributed systems
- Two orthogonal sub-languages: Data: abstract data types (ActOne)
 - sorts and operations
 - algebraic equations

Processes: process algebras (~CCS, CSP, Circal)

- parallel processes (interleaving semantics)
- message-passing communication



LOTOS types: An example

type FLOOR is BOOLEAN sorts FLR

opns

LOWER (*! constructor *), MIDDLE (*! constructor *), UPPER (*! constructor *), ERROR (*! constructor *) :-> FLR INCR, DECR : FLR -> FLR _____, _<_ , _>_ : FLR, FLR -> BOOL

eqns

```
forall X, Y:FLR
ofsort FLR
INCR (LOWER) = MIDDLE;
INCR (MIDDLE) = UPPER;
(* else *) INCR (X) = ERROR;
```

ofsort FLR DECR (MIDDLE) = LOWER; DECR (UPPER) = MIDDLE; (* else *) DECR (X) = ERROR;

ofsort BOOL
 X == X = true;
 (* else *) X == Y = false;

```
ofsort BOOL
LOWER < MIDDLE = true;
LOWER < UPPER = true;
MIDDLE < UPPER = true;
(* else *) X < Y = false;</pre>
```

```
ofsort BOOL
X > Y = Y < X;
endtype
```



LOTOS processes: An example



```
ELEVATOR [CALL, GO, UP, DOWN] (LOWER, LOWER)

|[CALL, GO]|

(

CLIENT [CALL, GO] (LOWER, UPPER)

|||

CLIENT [CALL, GO] (UPPER, MIDDLE)

)
```



LOTOS processes (cont'd)

```
process ELEVATOR [CALL, GO, UP, DOWN] (CURRENT, TARGET: FLR) : noexit :=
   [TARGET > CURRENT] ->
    UP !INCR (CURRENT);
      ELEVATOR [CALL, GO, UP, DOWN] (INCR (CURRENT), TARGET)
   []
   [TARGET < CURRENT] ->
    DOWN !DECR (CURRENT);
      ELEVATOR [CALL, GO, UP, DOWN] (DECR (CURRENT), TARGET)
   []
  [TARGET == CURRENT] ->
    CALL ?NEW TARGET:FLR;
      ELEVATOR [CALL, GO, UP, DOWN] (CURRENT, NEW_TARGET)
    []
    GO ?NEW_TARGET:FLR;
      ELEVATOR [CALL, GO, UP, DOWN] (CURRENT, NEW_TARGET)
endproc
```



Labelled Transition Systems (LTSs)

• LTS: the standard semantic model for actionbased languages (including LOTOS)



- $M = (S, A, T, s_0)$, where:
 - S: set of states
 - A: set of labels (information attached to transitions)
 - $T \in S \times A \times S$: transition relation
 - $s_0 \in S$: initial state



LTSs and verification

- LTSs provide a standard basis for many automated verification algorithms
- Examples:
 - Reachable state analysis (LTS exploration)
 - Equivalence checking (bisimulations)
 - Model checking (modal mu-calculus)



Computer representations of LTSs

- "Explicit" LTS (or LTS "in extenso"): LTS defined by the exhaustive list of its states and transitions
 - state successors and state predecessors are available: the LTS can be explored both forward and backward
 - this enables both global and local (on the fly) verification
 - CADP provides the BCG tools for explicit (finite) LTSs
- "Implicit" LTS (or LTS "in comprehension"): LTS defined by its initial state and successor function
 - state predecessors are not known: only forward exploration (local verification) is allowed
 - CADP provides the Open/Caesar tools for implicit LTSs



CADP tools for LOTOS





CAESAR.ADT

- Translation LOTOS ADTs \rightarrow C
 - each LOTOS sort \rightarrow one C type
 - each LOTOS operation \rightarrow one C function
- Assumptions wrt standard LOTOS
 - difference between constructors and non-constructors
 - free constructors
 - equations seen as rewrite rules with pattern-matching and priorities
- Specialized C code generation
 - Oriented towards model checking
 - Optimize memory first, then speed



CAESAR.ADT (cont'd)

Compiling data strutures

- dynamic data structures (lists, trees, ...) allowed
- optimized memory implementation:
 - minimal number of bits
 - permutation of "record" fields
 - common subterm sharing
- Compiling functions
 - pattern matching compiling algorithm
 - ad hoc optimisations





CADP tools for explicit LTSs



Motivations

- How to store large LTSs in computer files?
- Existing text-based formats are not satisfactory:
 - disk space consuming (hundreds of Mbytes, Gbytes)
 - slow (read/write operations are costly)
 - sometimes ambiguous



The BCG format of CADP

- BCG (Binary-Coded Graphs):
- a compact file format for storing LTSs
- a set of APIs
- a set of software libraries
- a set of tools (binary programs and scripts)

implementation : 30,000 lines of C code
BCG is shipped as a component of CADP
All the CADP tools use BCG consistently



The BCG libraries and APIs

- **bcg_write:** API to create a BCG file
- **bcg_read:** API to read a BCG file
- **bcg_transition:** API to store a transition relation in memory:
 - successor function, or
 - predecessor function, or
 - successor and predecessor functions



The basic BCG tools

- bcg_info: extract info from a BCG file
- **bcg_io:** convert BCG \leftrightarrow other formats
- **bcg_labels:** hide and/or rename labels
- bcg_draw, bcg_edit: visualize LTSs







- CADP supports 3 such tools:
 - ALDEBARAN (Verimag)
 - FC2TOOLS (INRIA/Meije) interfaced with CADP
 - BCG_MIN (INRIA/VASY) the most recent
- Various equivalences supported: strong, observational, branching, safety...



BCG_MIN: Minimization of LTSs

- This tool handles several types of LTSs:
 - standard LTSs
 - ✓ strong bisimulation [~Kanellakis-Smolka] ✓ branching bisimulation [Groote-Vaandrager] ✓ better performances than Aldebaran and Fc2min ✓ better display of equivalence classes

 - stochastic LTSs
 - mixed models
 - probabilistic LTSs "prob p" transitions
 - "**rate** λ " transitions
 - "*label* ; **prob** *p*" or "*label* : rate λ " transitions
- Joint work with Holger Hermanns



Model checking tools: XTL

XTL:

- a query language for LTSs (encoded in BCG)
- a compiler for this language



XTL: Principles and applications

- Main features of XTL
 - functional language with model checking features
 - special types: states, state sets, transitions, transition sets, labels...
 - access to the typed objects of the BCG file
- Applications of XTL
 - libraries: HML, CTL, ACTL, mu-calculus
 - rapid prototyping of temporal logics
 - temporal logics extended with value passing



XTL: An example

The $\langle A \rangle F$ modality of HML (Hennessy-Milner logic) can be expressed in XTL

 $\langle A \rangle F$ denotes the set of states S that

- lead to states satisfying F
- following transitions satisfying A

```
def Diamond (A:labelset, F:stateset):stateset =
    { S:state where
    exists T:edge among out (S) in
        (label (T) among A) and (target (T) among F)
        end_exists }
end_def
```



CADP tools for *implicit* LTSs



Motivations

- Most model checkers are dedicated to one particular input language (Spin, SMV, ...)
- They can't be reused easily for other languages
- Idea: introduce modularity by separating
 - language-dependent aspects: compiling language into LTS model
 - language-independent algorithms: algorithms for LTS exploration



OPEN/CAESAR



OPEN/CAESAR libraries

A set of predefined data structures

- EDGE : list of transitions (e.g., successor lists)
- HASH : catalog of hash functions
- STACK_1 : stacks of states and/or labels
- DIAGNOSTIC_1 : set of execution paths
- TABLE_1 : state tables
- BITMAP : Holzmann's "bit state" tables

Specific primitives for on the fly verification

- possibility to attach additional information to states
- stack or table overflow => backtracking
- etc.



OPEN/CAESAR applications

- EXECUTOR : random walk
- SIMULATOR : interactive simulation (textual)
- XSIMULATOR : interactive simulation (graphical)
- GENERATOR : exhaustive LTS generation
- REDUCTOR : LTS generation with safety reduction
- PROJECTOR : LTS generation with constraints
- TERMINATOR : Holzmann's bit-space algorithm
- EXHIBITOR : search paths defined by reg. expr.
- EVALUATOR : evaluation of mu-calculus formulas
- TGV : test sequence generation



#include "caesar_graph.h"
#include "caesar_edge.h"
#include "caesar_table_1.h"

An example: GENERATOR

TYPE_TABLE_1 t;TYPE_STATE s1, s2;TYPE_EDGE e1_en, e;TYPE_LABEL 1;TYPE_INDEX_TABLE_1 n1, n2TYPE_POINTER dummy;

INIT_GRAPH (); INIT_EDGE (FALSE, TRUE, TRUE, 0, 0); CREATE_TABLE_1 (&t, 0, 0, 0, 0, TRUE, NULL, NULL, NULL); if (t == NULL) ERROR ("not enough memory for table");

```
START_STATE ((TYPE_STATE) PUT_BASE_TABLE_1 (t));
PUT_TABLE_1 (t);
while (!EXPLORED_TABLE_1 (t)) {
    s1 = (TYPE_STATE) GET_BASE_TABLE_1 (t);
    n1 = GET_INDEX_TABLE_1 (t);
    GET_TABLE_1 (t);
```

```
CREATE_EDGE_LIST (s1, &e1_en, 1);
if (TRUNCATION_EDGE_LIST () != 0) ERROR ("not enough memory for edge lists");
```

```
ITERATE_LN_EDGE_LIST (e1_en, e, l, s2) {
    COPY_STATE ((TYPE_STATE) PUT_BASE_TABLE_1 (t), s2);
    (void) SEARCH_AND_PUT_TABLE_1 (t, &n2, &dummy);
    print_edge (n1, STRING_LABEL (l), n2);
}
DELETE EDGE LIST (&e1 en);
```



Three recent OPEN/CAESAR tools

- Three different application areas:
- Simulation:
 - => OCIS (Open/Caesar Interactive Simulator)
- Model checking:

=> EVALUATOR 3.0

Test generation:
 => TGV



OCIS (Open/Caesar Interactive Simulator)



OCIS (Open/Caesar Interactive Simulator)



- language-independent
- tree-like scenarios
- save/load scenarios
- source code access
- dynamic recompile
- support for tasks and MSCs



Evaluator 3.0

On-the-fly model checking of regular alternation-free mu-calculus



TGV

On-the-fly generation of test cases according to hand-written test purposes



CADP tools for compositional verification



Compositional verification

- A significant mean to fight state explosion
- Principle:
 - Generation of separate processes
 - Minimization of processes
 - Recombination of minimized processes
- CADP provides numerous tools for compositional verification



The SVL language

- SVL: a scripting language supplied with CADP
- Two motivations:
 - Provide a textual interface for all the tools of CADP (+ Fc2Tools)
 - Enable an easy writing of compositional verification scenarios
- Targeted audience:
 - Novice users (simple verifications)
 - Expert users (sophisticated verifications, namely compositional)



Script SVL: Example 1

```
% DEFAULT_LOTOS_FILE="bitalt_protocol.lotos"
"bitalt_protocol.exp" =
   leaf strong reduction of
     hide SDT, RDT, RDTe, RACK, SACK, SACKe in
          (BODY_TRANSMITTER | | BODY_RECEIVER)
          SDT, RDT, RDTe, RACK, SACK, SACKe]
          (MEDIUM1 | | MEDIUM2)
        );
"bitalt_dead.seq" = deadlock of "bitalt_protocol.exp";
"bitalt_live.seq" = livelock of "bitalt_protocol.exp";
branching comparison using fly with aldebaran
       "bitalt_protocol.exp" == "bitalt_service.lotos";
```



Script SVL: Example 2

```
% DEFAULT_LOTOS_FILE="rel_rel.lotos"
"crash_trans.bcg" = strong reduction of CRASH_TRANSMITTER;
"rel_rel.bcg" = generation of leaf strong reduction of
  hide R_T1, R_T2, R_T3, R12, R13, R21, R23, R31, R32 in
  ( ( ( RECEIVER_NODE_1 - | |? "r1_interface.lotos")
        [R12, R21, R13, R31]
          (RECEIVER_NODE_2 - | |? "r2_interface.lotos")
          [R23, R32]
           (RECEIVER_NODE_3 - | |? "r3_interface.lotos")
       ) - [R_T2, R_T3] | "crash_trans.bcg"
       ) - [R_T1, R_T2, R_T3] | "crash_trans.bcg"
   |[R_T1, R_T2, R_T3]|
   "crash_trans.bcg");
```





CADP Architecture



A layered software architecture





The EUCALYPTUS graphical user interface

- File types
- Contextual menus
- Dialog boxes
- Multiple tools: CADP, FC2
- Online help





Conclusion



Conclusion

- CADP: a rich platform for protocol and distributed systems engineering
- An open, extensible toolbox through well-defined APIs
- Several architectures supported:
 - Sun running SunOS or Solaris
 - PC running Linux
 - PC running Windows
- Large dissemination (figures dated 2001):
 - CADP licensed to 256 sites
 - licenses granted for 950 machines in 2001
 - **53 case-studies** done using CADP
 - 11 research tools built using CADP



More information...

http://www.inrialpes.fr/vasy/cadp



